

REMOTE NETWORK MANAGEMENT SYSTEM

FIELD OF THE INVENTION

The present invention relates generally to a remote
5 network management system for remotely controlling network
and computer equipment from one or more local user
workstations through a remote control device.
Specifically, a keyboard, video monitor, and cursor control
device attached to a user workstation are utilized to
10 remotely control domain servers, file/print servers,
headless servers, network appliances, serial IT equipment,
switches, routers, firewalls, security interfaces,
application servers, load balancers, and environmental
controls as their associated power supplies are connected
15 to a remote control device.

BACKGROUND OF THE INVENTION

In many situations, it is desirable to manage
networking equipment, servers, and computers located at a
20 location remote from the system administrator. If the
distance is great enough, the Internet is commonly utilized
to control computers from a remote location. For example,
a software program such as pcAnywhere may be utilized to
access a remote computer over the Internet or a LAN

utilizing the keyboard, video monitor, and cursor control device attached to a local user workstation. Remote computer access programs, such as pcAnywhere, typically require that host software is installed on the remote computer and client software is installed on the user workstation. To access a remote computer, a user of the user workstation selects the desired remote computer from a list and enters the appropriate username and password. Once access has been granted to the remote computer, the user utilizes the keyboard, video monitor, and cursor control device attached to the local user workstation to access and operate the remote computer.

Hardware solutions also exist for operating a remote computer from a user workstation over the Internet or via a modem. In contrast to software solutions, hardware solutions do not typically require host and/or client software. Instead, hardware solutions typically utilize a keyboard, video monitor, and mouse ("KVM") switch which is accessible over the Internet or LAN via a common protocol, such as TCP/IP. The hardware solutions may also utilize a modem to connect to the Internet. Generally, a user or system administrator accesses the remote computers attached to the KVM switch utilizing an Internet web-browser or client software associated with the KVM switch. Once the

remote computer has been selected, the remote computer's video signal is routed to the user workstation's video monitor and a user may then utilize a keyboard and/or mouse to control the remote computer. The KVM switch may
5 additionally include a connection to the power source of the remote computer for a hard reboot in case of system failure.

The aforementioned hardware and software solutions generally utilize compression algorithms to reduce the
10 necessary bandwidth required to transmit the video signals. For example, the remote network management system of the present invention uses the compression algorithm disclosed in application serial no. 10/233,299, which is incorporated herein by reference, to reduce and compress the digital
15 data that must be transmitted to the remote computers and/or video display devices. Generally, video signals generated by a personal computer have both spatial and interframe redundancies. For example, in a near idle personal computer, the only change between successive
20 frames of video might be the blinking of a cursor. Even as a user types a document, a majority of the screen does not change over a period of time. Hence, the compression algorithm used by the present invention takes advantage of these redundancies, both between successive frames of video

and within each individual frame, to reduce the amount of digital video signal data that is transmitted to the remote computers and/or video display devices. Reducing the amount of digital data transmitted over the communication
5 medium decreases communication time and decreases the required bandwidth.

Most forms of video compression known in the art require complicated calculations. For example, Moving Pictures Experts Group ("MPEG") video compression
10 algorithms use the discrete cosine transform as part of its algorithm. Also, the MPEG standard relies on the recognition of "motion" between frames, which requires calculation of motion vectors that describe how portions of the video image have changed over a period of time. Since
15 these algorithms are calculation intensive, they either require expensive hardware or extended transmission times that allow sufficient time for slower hardware to complete the calculations.

In addition to complexity, many existing video
20 compression techniques are lossy (i.e., they do not transmit all of the video signal information in order to reduce the required bandwidth). Typically, such lossy techniques either reduce the detail of a video image or reduce the number of colors utilized. Although reducing

the number of colors could be part of an adequate
compression solution for some computer management systems
applications, in many other applications, such a result
defeats the intended purposes of the computer management
5 system.

The following references, which are discussed below,
were found to relate to the field of computer management
systems: Perholtz *et al.* U.S. Patent No. 5,732,212
("Perholtz"), Beasley U.S. Patent No. 6,112,264
10 ("Beasley"), Pinkston, II *et al.* U.S. Patent No. 6,378,009
("Pinkston"), Thornton *et al.* U.S. Patent No. 6,385,666
("Thornton"), and Wilder *et al.* U.S. Patent No. 6,557,170
("Wilder").

Perholtz discloses a method and apparatus for coupling
15 a local user workstation, including a keyboard, mouse,
and/or video monitor, to a remote computer. Perholtz
discloses a system wherein the remote computer is selected
from a menu displayed on a standard size personal computer
video monitor. Upon selection of a remote computer by the
20 system user, the remote computer's video signals are
transmitted to the local user workstation's video monitor.
The system user may also control the remote computer
utilizing the local user workstation's keyboard and
monitor. The Perholtz system is also capable of bi-

directionally transmitting mouse and keyboard signals between the local user workstation and the remote computer. The remote computer and the local user workstation may be connected either via the Public Switched Telephone System ("PSTN") and modems or via direct cabling.

Similar to Perholtz, Beasley discloses a specific implementation of a computerized switching system for coupling a local keyboard, mouse and/or video monitor to one of a plurality of remote computers. In particular, a first signal conditioning unit includes an on-screen programming circuit that displays a list of connected remote computers on the local video monitor. To activate the menu, a user depresses, for example, the "print screen" key on the local keyboard. The user selects the desired computer from the list using the local keyboard and/or mouse.

According to Beasley, the on-screen programming circuit requires at least two sets of tri-state buffers, a single on-screen processor, an internal synchronization generator, a synchronization switch, a synchronization polarizer, and overlay control logic. The first set of tri-state buffers couples the red, green, and blue components of the video signals received from the remote computer to the video monitor. That is, when the first set

of tri-state buffers are energized, the red, green, and blue video signals are passed from the remote computer to the local video monitor through the tri-state buffers.

When the first set of tri-state buffers are not active, the
5 video signals from the remote computer are blocked.

Similarly, the second set of tri-state buffers couples the outputs of the single on-screen processor to the video monitor. When the second set of tri-state buffers is energized, the video output of the on-screen programming
10 circuit is displayed on the local video monitor. When the second set of tri-state buffers is not active, the video output from the on-screen programming circuit is blocked. Alternatively, if both sets of tri-state buffers are energized, the remote computer video signals are combined
15 with the video signals generated by the on-screen processor prior to display on the local video monitor.

The on-screen programming circuit disclosed in Beasley also produces its own horizontal and vertical synchronization signals. To dictate which characters are
20 displayed on the video monitor, the CPU sends instructional data to the on-screen processor. This causes the on-screen processor to retrieve characters from an internal video RAM for display on the local video monitor.

The overlaid video image produced by the on-screen processor, namely a Motorola MC141543 on-screen processor, is limited to the size and quantity of colors and characters that are available with the single on-screen processor. In other words, the Beasley system is designed to produce an overlaid video that is sized for a standard size computer monitor (i.e., not a wall-size or multiple monitor type video display) and is limited to the quantity of colors and characters provided by the single on-screen processor.

During operation of the Beasley system, a remote computer is chosen from the overlaid video display. Thereafter, the first signal conditioning unit receives keyboard and mouse signals from the local keyboard and mouse and generates a data packet for transmission to a central cross point switch. The cross point switch routes the data packet to the second signal conditioning unit, which is coupled to the selected remote computer. The second signal conditioning unit then routes the keyboard and mouse command signals to the keyboard and mouse connectors of the remote computer. Similarly, video signals produced by the remote computer are routed from the remote computer through the second signal conditioning unit, the cross point switch, and the first signal

conditioning unit to the local video monitor. The horizontal and vertical synchronization video signals received from the remote computer are encoded on one of the red, green or blue video signals. This encoding reduces the quantity of cables required to transmit the video signals from the remote computer to the local video monitor.

Pinkston discloses a keyboard, video, mouse ("KVM") switching system capable of coupling to a standard network (e.g., a Local Area Network) operating with a standard network protocol (e.g., Ethernet, TCP/IP, etc.). The system of Pinkston couples a central switch to a plurality of computers and at least one user station having a keyboard, video monitor, and mouse. The central switch includes a network interface card ("NIC") for connecting the central switch to a network, which may include a number of additional computers or remote terminals. Utilizing the Pinkston system, a user located at a remote terminal attached to the network may control any of the computers coupled to the central switch.

Thornton discloses a computer system having remotely located I/O devices. The system of Thornton includes a computer, a first interface device, and a remotely located second interface device. The first interface device is

coupled to the computer and the second interface device is coupled to a video monitor and as many as three I/O devices (e.g., keyboard, mouse, printer, joystick, trackball, etc.) such that a human interface is created. The first and
5 second interface devices are coupled to each other via a four wire cable. The first interface device receives video signals from the connected computer and encodes the horizontal and vertical synchronization signals of the received video signals onto at least one of the red, green,
10 and blue components of the video signal. The first interface device also encodes the I/O signals received from the connected computer into a data packet for transmission over the fourth wire in the four wire cable. Thereafter, the encoded, red, green, and blue components of the video
15 signals and the data packet are transmitted to the second interface device located at the human interface. The second interface device decodes the encoded red, green, and blue components of the video signal, separates the encoded horizontal and vertical synchronization signals, and
20 decodes the I/O signal data packet. The video signal and the synchronization signals are then output to the video monitor attached to the second interface and the decoded I/O signals are routed to the proper I/O device, also attached to the second interface. The second interface

device may optionally include circuitry to encode I/O signals received from the I/O devices attached to the second interface for transmission to the first interface device.

5 Wilder discloses a keyboard, video, mouse, and power switching ("KVMP") apparatus for connecting a plurality of computers to one or more user stations having an attached keyboard, video monitor, and mouse. On screen display ("OSD") circuitry embedded within the KVMP switching
10 apparatus allows a user located at a user station to select and operate any one of the computers utilizing the keyboard, video monitor, and mouse attached to the user station. Secondary switching circuitry located within the KVMP switching apparatus allows a user located at a user
15 station to additionally control the electrical power supply supplying each computer.

 In view of the foregoing, a need clearly exists for a self-contained remote network management system capable of operating and controlling networking equipment, servers,
20 and computers connected to a remote control switching unit. Furthermore, such a system should allow a user to control the power supply attached to the remote networking equipment, servers, and computers. The system should aid

in managing remote network environments, thereby reducing the need to have an on-site system administrator.

SUMMARY OF THE INVENTION

5 The present invention provides a self-contained remote network management system for administering a remote computer networking environment from one or more local user workstations with attached peripheral devices (i.e., keyboard, video monitor, cursor control device, etc.). The
10 remote network management system of the present invention allows a user located at a user workstation to access, operate, and control networking equipment, servers, and computers located at a remote location. The remote network management system also allows a user to control the power
15 supply to each piece of remote equipment. The networking equipment (e.g., hubs, switches, routers, etc.) is typically controlled via a serial interface. In contrast, servers and computers are controlled and operated utilizing a keyboard, video monitor, and mouse.

20 The remote networking equipment, servers, and computers are all connected to a central remote management unit ("RMU"), and in turn, the RMU is connected to the Internet or a LAN via an Ethernet or modem connection. The RMU has serial ports for connection to the networking

equipment as well as keyboard, video, and cursor control device ports for connection to the servers and computers.

The RMU additionally contains a port for connection to a power supply capable of controlling the power to the

5 networking equipment, servers, and computers. Standard cabling is utilized to connect the networking equipment, servers, and computers to the appropriate ports on the RMU.

The RMU also provides compatibility between various operating systems and/or communication protocols, including

10 but not limited to, those manufactured by Microsoft Corporation ("Microsoft") (Windows), Apple Computer, Inc. ("Apple") (Macintosh), Sun Microsystems, Inc. ("Sun") (Solaris), Digital Equipment Corporation ("DEC"), Compaq Computer Corporation ("Compaq") (Alpha), International
15 Business Machines ("IBM") (RS/6000), Hewlett-Packard Company ("HP") (HP9000) and SGI (formerly "Silicon Graphics, Inc.") (IRIX).

To utilize the remote network management system of the present invention, a user first initiates a management

20 session by utilizing client software located on a user workstation to connect to the RMU. Alternatively, the user may utilize an Internet browser to connect to the RMU. The user is then prompted by the RMU to provide a user name and a password. The RMU is capable of storing multiple

profiles and different levels of access for each profile.

Once a user has been authenticated, the user is provided an

option menu on the user workstation's monitor produced by

option menu circuitry located in the RMU. The option menu

5 consists of a menu listing all the networking equipment,

servers, and computers at the remote location. The option

menu additionally contains a menu allowing a user to

control the power to each piece of remote equipment. The

user selects the desired networking equipment, server, or

10 computer by utilizing the keyboard and/or cursor control

device attached to the user workstation. Once a user makes

a selection, the user is provided access to the remote

equipment as if the user is physically located at the

remote site.

15 The RMU and the user workstation communicate via

TCP/IP. Before transmission via TCP/IP, the unidirectional

video signals (i.e., from the RMU to the user workstation)

are digitized by a frame grabber. This circuit captures

video output from the initiating computer at a speed of at

20 least 20 frames/second and converts the captured analog

video signals to a digital representation of pixels. Each

pixel is digitally represented with 5 bits for red, 5 bits

for green, and 5 bits for blue. The digital representation

is then stored in a raw frame buffer. The compression

algorithm then processes the digital data contained in the raw frame buffer. The compression algorithm is actually a combination of four sub-algorithms (i.e., the Noise Reduction and Difference Test ("NRDT"), Smoothing, Caching, and Bit Splicing/Compression sub-algorithms) as described in greater detail below.

After the video signals have arrived at the user workstation, decompression occurs. The user workstation operates as a decompression device by executing a decompression algorithm. Along with any transmitted video or data signals, the RMU transmits messages to the decompression devices regarding the portions of the video that yielded "cache" hits (i.e., portions of unchanged video). In response, the decompression device constructs the video frame based upon the transmitted video signals and the blocks of pixels contained in its local cache. Also, the decompression device updates its local cache with the new blocks of pixels received from the RMU. In this manner, the decompression device caches remain synchronized with the compression device cache. Both the compression device and the decompression device update their respective cache by replacing older video data with newer video data.

Furthermore, the video signals transmitted by the RMU have been compressed using a lossless compression

algorithm. Therefore, the decompression device (e.g., software on the user workstation) must reverse this lossless compression. This is done by identifying the changed portions of the video image, based upon flags transmitted by the RMU. From this flag information, the decompression device is able to reconstruct full frames of video.

In addition, the decompression device converts the video frame to its original color scheme by reversing a color code table ("CCT") conversion. The decompression device, like the RMU, locally stores a copy of the same CCT used to compress the video data. The CCT is then used to convert the video data received from the RMU to a standard RGB format that may be displayed on the monitor attached to the user workstation.

The decompression algorithm can be implemented in the remote network management system of the present invention in a variety of embodiments. For example, in one embodiment, it can be implemented as a software application that is executed by the user workstation. In an alternate embodiment, the decompression algorithm can be implemented to execute within a web browser such as Internet Explorer or Netscape® Navigator®. Such an embodiment eliminates the need for installation of application specific software on

the user workstation. Also, this embodiment allows the RMU to easily transmit the video signals to any user workstation with Internet capabilities, regardless of the distance at which the computer is located from the
5 initiating computer. This feature reduces the cabling cost associated with the remote network management system of the present invention.

Since the present invention can be used to display video signals at locations that may be at a great distance
10 from the RMU, it is important to ensure that the video signal transmission is secure. If the transmission is not secure, hackers, competitors, or other unauthorized users could potentially view confidential information contained within the video signals. Therefore, the remote network
15 management system of the present invention is designed to easily integrate with digital encryption techniques known in the art. In one embodiment of the present invention, a 128-bit encryption technique is used both to verify the identity of the RMU and to encrypt and decrypt the
20 transmitted video and data signals. In this embodiment, a 128-bit public key RSA encryption technique is used to verify the remote participant, and a 128-bit RC4 private key encryption is used to encrypt and decrypt the

transmitted signals. Of course, other encryption techniques or security measures may be used.

Finally, since the remote network management system of the present invention allows for platform independent
5 communications, the compression algorithm utilized does not employ operating system specific hooks, nor does it use platform specific GDI calls.

In the preferred embodiment, the compression algorithm described herein and in co-pending application serial no.
10 10/233,299 is used to transmit the video signals. However, the video transmission system is not limited to such an embodiment. Rather, this system may be employed with any compression algorithm without departing from the spirit of the invention.

15 Therefore, it is an object of the present invention to provide an improved, remote network management system that enables a user to control a remote networking environment from one or more local user workstations. Such a remote networking environment may include domain servers,
20 file/print servers, headless servers, network appliances, serial IT equipment, switches, routers, firewalls, security interfaces, application servers, load balancers, and environmental controls.

Further, it is an object of the present invention to provide a remote network management system that allows one or more local user workstations to access and operate remote networking equipment, servers, and computers
5 connected to a remote management unit.

It is another object of the present invention to provide a single, platform-independent remote network management system offering centralized, integrated, and secure control.

10 It is an additional object of the present invention to provide a network-independent remote network management system containing a modem for emergency access.

It is a further object of the present invention to provide a remote network management system capable of BIOS-
15 level control of KVM equipment and console-level control of serial devices.

Additionally, it is an object of the present invention to provide a remote network management system which provides a single consolidated view of all servers and
20 other connected devices from one screen via a web browser.

It is another object of the present invention to provide a remote network management system which contains a single sign-on and interface.

Additionally, it is an object of the present invention to provide a remote network management system which is upgradeable.

It is a further object of the present invention to
5 provide a remote network management system which provides high performance over low bandwidth connections including modem, wireless, cable, DSL, and fractional T1.

It is another object of the present invention to provide a remote network management system which utilizes a
10 video compression algorithm and frame-grabber technology to ensure the fastest possible transmission of high quality video.

Furthermore, it is an object of the present invention to provide a remote network management system including
15 built-in serial port buffering to provide views of recent console history.

It is still a further object of the present invention to provide a remote network management system that is easy to install and operate.

20 In addition, it is an object of the present invention to provide a remote network management system that is compact and provides readily accessible communications ports.

Further, it is an object of present invention to provide a remote network management system, which allows error-free communications between peripheral devices of a local user workstation and networking equipment, servers, and computers located at domain servers, file/print servers, headless servers, network appliances, serial IT equipment, switches, routers, firewalls, security interfaces, application servers, load balancers, and environmental controls.

It is also an object of the present invention to provide a remote network management system capable of controlling the power supply to remotely located networking equipment, servers, and computers.

Other objects, features, and characteristics of the present invention, as well as the methods of operation and functions of the related elements of the structure, and the combination of parts and economies of manufacture, will become more apparent upon consideration of the following detailed description with reference to the accompanying drawings, all of which form a part of this specification.

BRIEF DESCRIPTION OF THE DRAWINGS

A further understanding of the present invention can be obtained by reference to a preferred embodiment set

forth in the illustrations of the accompanying drawings. Although the illustrated embodiment is merely exemplary of systems for carrying out the present invention, both the organization and method of operation of the invention, in
5 general, together with further objectives and advantages thereof, may be more easily understood by reference to the drawings and the following description. The drawings are not intended to limit the scope of this invention, which is set forth with particularity in the claims as appended or
10 as subsequently amended, but merely to clarify and exemplify the invention.

For a more complete understanding of the present invention, reference is now made to the following drawings in which:

15 FIG. 1 is a schematic representation of a remote network management system according to the preferred embodiment of the invention illustrating the connection of a user workstation that includes a keyboard, video monitor, and cursor control device to networking equipment, servers,
20 and computers through a remote management unit ("RMU").

FIG. 2 is a screen-shot of an example option menu utilized to control the networking equipment, servers and computers.

FIG. 3A is a block diagram of the preferred embodiment of the RMU shown in FIG. 1 according to the preferred embodiment of the present invention illustrating the internal structure of the RMU and connectors for serial devices, keyboards, video monitors, cursor control devices, and a power supply.

FIG. 3B is a detailed block diagram of the serial card shown in FIG. 3A.

FIG. 3C is a detailed block diagram of the KVM port header shown in FIG. 3A.

FIG. 3D is a detailed block diagram of the video processor shown in FIG. 3A.

FIG. 4 depicts a flowchart of the compression algorithm utilized by the preferred embodiment of the RMU in accordance with the present invention.

FIG. 5A depicts a flowchart detailing the Noise Reduction and Difference Test and smoothing sub-algorithms of the compression algorithm utilized by the preferred embodiment of the present invention.

FIG. 5B depicts a flowchart that details the caching and bit splicing/compression sub-algorithms of the compression algorithm utilized by the preferred embodiment of the present invention.

FIG. 6 depicts a flowchart that details the nearest match function and its integration with the CCT of the compression algorithm utilized by the preferred embodiment of the present invention.

5 FIG. 7 depicts a flowchart that details the Noise Reduction and Difference Test sub-algorithm of the compression algorithm utilized by the preferred embodiment of the present invention.

10 FIG. 8 depicts an example application of the Noise Reduction and Difference Test sub-algorithm to a sample block of pixels as performed by the compression algorithm utilized by the preferred embodiment of the present invention.

15 FIG. 9 depicts a detailed flowchart of the operation of the decompression algorithm used by the preferred embodiment of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

20 As required, a detailed illustrative embodiment of the present invention is disclosed herein. However, techniques, systems and operating structures in accordance with the present invention may be embodied in a wide variety of forms and modes, some of which may be quite different from those in the disclosed embodiment.

Consequently, the specific structural and functional details disclosed herein are merely representative, yet in that regard, they are deemed to afford the best embodiment for purposes of disclosure and to provide a basis for the
5 claims herein which define the scope of the present invention. The following presents a detailed description of the preferred embodiment (as well as some alternative embodiments) of the present invention.

Referring first to FIG. 1, depicted is the
10 architecture of the preferred embodiment of a remote network management system in accordance with the present invention. Specifically, a remote network management system is shown comprising user workstation 101 including keyboard 103, video monitor 105, and cursor control device
15 107, remote management unit ("RMU") 109, Internet/LAN/WAN 108, public switched telephone network ("PSTN") 106, serial devices 111a and 111b, servers 113a and 113b, remote computers 115a and 115b, and power supply 117. Preferably, user workstation 101 and RMU 109 are connected to
20 Internet/LAN/WAN 108 via communication lines 119 and 121, respectively. Although CAT 5 cabling is the preferred cabling for communication lines 119 and 121, other cabling may be used, such as coaxial, fiber optic or multiple CAT 5 cables. CAT 5 cabling is preferred because it reduces

cabling cost while maintaining the strength of signals that are transmitted over an extended distance. Alternatively, wireless networking equipment may also be utilized to connect RMU 109 to Internet/LAN/WAN 108 and serial devices 111a and 111b, servers 113a and 113b, computers 115a and 115b, and power supply 117. Similarly, wireless networking equipment may also be utilized to connect user workstation 101 to Internet/LAN/WAN 108.

In an alternate embodiment, user workstation 101 may utilize PSTN 106 to connect to RMU 109. If PSTN 109 is utilized to connect to RMU 109, communication lines 120 and 122 would preferably be CAT 3 cables. As an example, this means of communication may be utilized in emergency situations, such as if Internet/LAN/WAN 108 is not functioning properly.

Communication lines 119 and 121 are connected to user workstation 101 and RMU 109 by plugging each end into a RJ-45 socket located on the respective pieces of equipment to be coupled by the CAT 5 cable. Although RJ-45 sockets and plugs are preferred, other types of connector may be used, including but not limited to RJ-11, RG-58, RG-59, British Naval Connector ("BNC"), and ST connectors.

The remote management system includes local user workstation 101, preferably comprising dedicated peripheral

devices such as keyboard 103, video monitor 105 and/or cursor control device 107. Other peripheral devices may also be located at workstation 101, such as a printer, scanner, video camera, biometric scanning device,

5 microphone, etc. Each peripheral device is directly or indirectly connected to user workstation 101, which is attached to Internet/LAN/WAN 108 via communication line 119. Of course, wireless peripheral devices may also be used with this system. In a preferred mode of operation, 10 all electronic signals (i.e., keyboard signals and cursor control device signals) received at user workstation 101 from attached peripheral devices are transmitted to Internet/LAN/WAN 108 via communication line 119.

Thereafter, the signals are transmitted to RMU 109 via

15 communication line 121. RMU transmits the received signals to the respective remote equipment, which, in this figure, includes serial devices 111a and 111b, servers 113a and 113b, computers 115a and 115b, and power supply 117.

RMU 109 may be compatible with all commonly used, 20 present day computer operating systems and protocols, including, but not limited to, those manufactured by Microsoft (Windows), Apple (Macintosh), Sun (Solaris), DEC, Compaq (Alpha), IBM (RS/6000), HP (HP9000) and SGI (IRIX). Additionally, local devices may communicate with remote

computers via a variety of protocols including Universal Serial Bus ("USB"), American Standard Code for Information Interchange ("ASCII") and Recommend Standard-232 ("RS-232").

5 Serial devices 113a and 113b are connected to RMU 109 via communication lines 112a and 112b, respectively. Preferably, communication lines 112a and 112b are CAT 5 cables terminated with RJ-45 connectors. However, a special adapter may be required to properly connect
10 communication lines 112a and 112b to serial devices 111a and 111b since not all serial devices are outfitted with RJ-45 ports. For example, if serial device 111a only contained a serial port, the adapter would interface the RJ-45 connector of communication line 112a to the serial
15 port located on serial device 111a.

 Similarly, power supply 117 is connected to RMU 109 via communication line 118. Preferably, communication line 118 is a CAT 5 cable terminated with an RJ-45 connector on each end.

20 Servers 113a and 113b and computers 115a and 115b are connected to RMU 109 via communication lines 114a, 114b, 116a, and 116b, respectively. Preferably, communication lines 114a, 114b, 116a, and 116b are three-to-one coaxial cables which allow the keyboard, video, and cursor control

device ports of servers 113a and 113b and computers 115a and 115b to be connected to a single port on RMU 109 as shown.

To connect to the remote networking environment for
5 administration and access, a user initiates a remote
management session at user workstation 101. The user first
accesses client software located using workstation 101,
which prompts the user for a user name and password.
However, the system may utilize any combination of
10 identification data to identify and/or authenticate a
particular user. Utilizing the attached keyboard 103,
cursor control device 107 or other peripheral device, the
user enters the user name and password. Once the user name
and password have been entered, user workstation 101
15 connects to Internet/LAN/WAN 108 via communication line
119. User workstation 101 may connect to Internet/LAN/WAN
108 in a variety of ways. For example, user workstation
101 may be connected to Internet/LAN/WAN 108 through an
Ethernet connection. In this example, communication line
20 119 would be a CAT 5 cable. The connection to
Internet/LAN/WAN 108 may also be accomplished through a
wireless connection which precludes the need for
communication line 119. For example, RMU 109 may utilize

standard Wireless Fidelity ("Wi-Fi") networking equipment to communicate with Internet/LAN/WAN 108.

Alternatively, user workstation 101 may connect to RMU 109 via PSTN 106 by utilizing a modem connection. In this
5 alternative example, communication lines 120 and 122 would be CAT 3 cables.

The username and password are then routed through Internet/LAN/WAN 108 to RMU 109 via communication line 121. RMU 109 receives the username and password and
10 authenticates the user located at user workstation 101. Once the user has been authenticated by RMU 109, an option menu circuit located in RMU 109 provides an option menu to user 101 via monitor 105 listing all the devices accessible through RMU 109. The user makes selections from this
15 option menu utilizing keyboard 103, cursor control device 105, or some other peripheral device attached to user workstation 101.

As shown in FIG. 2, option menu 201 consists of device list 203, first desktop window 205, power control window
20 207, second desktop window 209, and serial device window 211. Device list 203 lists all active and inactive devices connected to RMU 109. A user utilizes this menu to select the desired device for control. In this example, first desktop window 205 displays the desktop of one of the

remote computers. By selecting first desktop window 205, a user may utilize keyboard 103, cursor control device 107, or some other peripheral device to control the displayed remote computer. In a similar manner, a user may utilize
5 power control window 207 to access and operate power supply 117. Power control window 207 displays a list of all devices connected to power supply 117 as well as the status of each attached device such as average power utilized, RMS current, RMS voltage, internal temperature, etc. Power
10 control window 207 is primarily utilized to cycle the power to the devices attached to power supply 117. However, since power supply 117 is programmable, power control window 207 may be utilized to perform any functions possible with power supply 117.

15 Second desktop window 209 is utilized to access and operate a second remote computer or server. Serial device window 211 is utilized to operate and access any remote serial device attached to remote management unit 109. Serial device window 211 displays the current output
20 produced by the serial device as well as the previous output produced by the serial device. The previous output of the serial device is stored in a buffer located in RMU 109.

Preferably, option menu 201 consists of a menu in which the attached devices are arranged by their connection to RMU 109. For example, serial devices 111a and 111b preferably would be listed in a menu different from servers 113a and 113b and computers 115a and 115b. The option menu also consists of a sub-menu for controlling power supply 117.

RMU 109 may additionally contain an attached keyboard 123, cursor control device 125, and video monitor 127 which allow a user local to RMU 109 to control the attached serial devices 111a and 111b, servers 113a and 113b, and computers 115a and 115b, power supply 117, etc. Keyboard 123, cursor control device 125, and video monitor 127 may also be utilized to configure RMU 109 locally. Keyboard 123, cursor control device 125, and video monitor 127 are connected to RMU 109 via interface cable 129. Alternatively, keyboard 123, cursor control device 125, and video monitor 127 may be connected to RMU 109 via standard keyboard, cursor control device, and video monitor connectors.

Referring next to FIG. 3A, depicted is the preferred embodiment of RMU 109 according to the present invention. Keyboard and mouse signals arrive at RJ-45 port 201 from Internet/LAN/WAN 108 via communication line 121. RMU 109

consists of RJ-45 port 201, RJ-11 port 202, Ethernet connector 205, modem module 204, communications port connector 206, CPU 207, communications port connector 208, PCI riser card 209, serial card 211, video processor 212, serial ports 213, frame grabber 215, KVM port header 217, KVM ports 219, power supply 221, power port 223, reset circuitry 225, local KVM port 227, and option menu circuit 229. As shown, the keyboard and/or cursor control device signals initially arrive at RJ-45 port 201 if RMU 109 is connected to Internet/LAN/WAN 108 via an Ethernet connection. The signals are then transmitted to Ethernet connector 205 which depacketizes the signals.

Alternatively, the signals may arrive from PSTN 106 at RJ-11 port 202 if the keyboard and/or cursor control device signals were transmitted via a modem. In this case, the signals are transmitted to modem module 204, which demodulates the received signals, and subsequently to communications port connector 206 which depacketizes the signals.

From Ethernet connector 205 or communications port connector 206, the keyboard and/or cursor control device signals are then transmitted to CPU 207 via video processor 212. CPU 207 utilizes routing information contained within the keyboard and/or cursor control device signals to

determine the proper destination for the keyboard and cursor control device signals. If the keyboard and cursor control device signals specify a command to power supply 117, CPU 207 interprets the received command (e.g.,
5 utilizing a look-up table) and sends the proper command to power supply 117 via communications port connector 208 and power port 210. Preferably, power port 210 is an RJ-45 connector to allow the RMU to interface with a power strip and control it as if it were a serial device.

10 If CPU 207 determines that the keyboard and cursor control device signals contain a serial device routing instruction, the keyboard and cursor control device signals are transmitted to serial card 211 through PCI riser card 209. As shown in FIG. 3B, serial port 211 consists of
15 UART/switch 301, serial transceivers 303, and programmable memory 305. Serial card 211 is capable of bidirectional signal transmission. When keyboard and/or cursor control device signals are being transmitted from PCI riser card 209 to serial port 213, the signals are initially
20 transmitted to UART/switch 301 which, utilizing data and logic stored in memory 305, determines the proper serial transceiver 303 to which the keyboard and/or cursor control device signals are to be sent. In the preferred embodiment of serial card 211, UART/switch 301 is an EXAR XR17c158.

Subsequently, the analog signals are transmitted to the appropriate serial transceiver 303 which converts the signals from a parallel format to a serial format. Serial transceiver 303 is preferably a HIN23E serial transceiver
5 from Intersil. The keyboard and/or cursor control device signals are then transmitted to serial port 213.

In contrast, when commands from serial device 111a or 111b are transmitted to CPU 207 via serial port 213, serial card 211, and PCI riser card 209, the commands are
10 initially transmitted to serial transceiver 303 which converts the serial commands to a parallel format. Subsequently, the commands are transmitted to UART/switch 301 which re-transmits the commands to CPU 207 via PCI riser card 209. CPU 207 interprets the received commands
15 and emulates a virtual terminal for display on video monitor 105. The present invention may incorporate any number of serial ports 213. In the example shown in FIG. 3A, two serial devices, 111a and 111b, are connected to serial ports 213a and 213b, respectively.

20 If CPU 207 determines that the keyboard and/or cursor control device signals are meant for servers 113a and 113b or computers 115a and 115b, CPU 207 transmits the keyboard and cursor control device signals through PCI riser card 209 and frame grabber 215 to KVM port header 217 which

transmits the signals to the appropriate KVM port 219. As shown in FIG. 3C, KVM port header 217 consists of switch 350, video switch 352, and UARTs 354. When keyboard and/or cursor control device signals are transmitted from KVM port 219 to KVM port header 217, the signals are initially received at UART 354. UART 354 converts the received serial keyboard and/or cursor control device signals to a parallel format. The converted keyboard and/or cursor control device signals are then transmitted to switch 350 which retransmits the signals to frame grabber 215.

In a similar manner, bi-directional keyboard and/or cursor control device signals are also transmitted from frame grabber 215 to KVM port 219. Keyboard and/or cursor control device signals received from frame grabber 215 are transmitted to switch 350 located in KVM port header 217. Utilizing control signals contained within the keyboard and/or cursor control device signals, switch 350 transmits the received keyboard and/or cursor control device signals to the appropriate UART 354. UART 354 then converts the keyboard and/or cursor control device signals from a parallel format to a serial format for transmission to KVM port 219.

KVM port header 217 also transmits uni-directional video signals received at KVM port 219 to frame grabber

215. The analog video signals received from KVM port 219 initially are transmitted to video switch 352. Video switch 352 then retransmits the video signals to frame grabber 215 which converts the received analog video
5 signals to a digital format.

Turning to FIG. 3D, after the video signals have been digitized by frame grabber 215, the digitized video signals are transmitted to video processor 212 via CPU 207. Video processor 212 consists of video-in port 370, R-out 376a, G-
10 out 376b, B-out 376c, pixel pusher 378, frame buffers 380, compression device 382, flash memory 384, RAM 386, microprocessor 388, and switch 390. Shown at the top of FIG. 3D, video-in port 370 receives the digitized video signals from CPU 207. The outputs of video-in port 370 are
15 shown as R-out 376a, G-out 376b, and B-out 376c, which represent the red component, green component, and blue component of the digitized video signal, respectively. Video-in port 370 outputs these digitized video signal components in the form of pixels, which are transmitted to
20 and stored in pixel pusher 378. Pixel pusher 378, flash memory 384, and Random Access Memory ("RAM") 386 communicate with microprocessor 388 via communication bus 387. Pixel pusher 378 also communicates with frame buffers 380 (e.g., raw frame buffer, compare frame buffer, etc.)

and compression device 382 via communication buses 379 and 381, respectively. The compression algorithm is executed by microprocessor 388. Generally, the compression operates as follows:

5 **Noise Reduction and Difference Test:**

As discussed above, digitization of the analog video signals is necessary to allow these signals to be transmitted via a digital communication medium (e.g., a network, LAN, WAN, Internet, etc.). However, a detrimental
10 side effect of the digitization process is the introduction of quantization errors and noise into the video signals. Therefore, the Noise Reduction and Difference Test sub-algorithm ("NRDT sub-algorithm") is designed to reduce the noise introduced during the digitization of the video
15 signals. In addition, the NRDT sub-algorithm simultaneously determines the differences between the recently captured frame of video (i.e., the "current frame") and the previously captured frame of video (i.e., the "compare frame").

20 First, the NRDT sub-algorithm divides the current frame, which is contained in the raw frame buffer, into 64 x 32 blocks of pixels. Alternatively, other sizes of blocks may be used (e.g., 8x8 pixels, 16x16 pixels, 32x32 pixels, etc.) based upon criteria such as the size of the

entire video frame, the bandwidth of the communication medium, desired compression yield, etc.

After the current frame is divided into blocks, a two-level threshold model is applied to the block of pixels to
5 determine whether it has changed with respect to the compare frame. These two thresholds are the "pixel threshold" and the "block threshold."

First, a given pixel is examined and the value of each of the three colors (i.e., red, green, and blue) of the
10 pixel is calculated with the value of its corresponding pixel in the compare frame. From this calculation, a distance value is computed. If the distance value is greater than the pixel threshold (i.e., the first threshold of the two-level threshold), this distance value is added
15 to a distance sum. This process is performed for each pixel in the block.

Next, after the distance value of all of the pixels in the block have been calculated and processed in the aforementioned manner, the resulting value of the distance
20 sum is compared to the block threshold (i.e., the second threshold of the two-level threshold). If the distance sum exceeds the block threshold, then this block of pixels is considered changed in comparison to the corresponding block of pixels in the compare frame. If a change is determined,

the compare frame, which is stored in the compare frame buffer, will be updated with the new block of pixels. Furthermore, the new block of pixels will be further processed and transmitted in a compressed format to the
5 user workstation.

In contrast, if the distance sum is not greater than the block threshold, the block of pixels is determined to be unchanged. Consequently, the compare frame buffer is not updated, and this block of pixels is not transmitted to
10 the user workstation. Eliminating the transmission of unchanged blocks of pixels reduces the overall quantity of data to be transmitted, thereby increasing transmission time and decreasing the required bandwidth.

The NRDT sub-algorithm is ideal for locating both a
15 large change in a small quantity of pixels and a small change in a large quantity of pixels. Consequently, the NRDT sub-algorithm is more efficient and more accurate than known percentage threshold algorithms that simply count the number of changed pixels in a block of pixels. With such
20 an algorithm, if a few pixels within the block of pixels have changed drastically (e.g., from black to white), the algorithm would consider the block of pixels to be unchanged since the total number of changed pixels would not exceed the percentage threshold value. This result

will often lead to display errors in the transmission of computer video.

Consider, for example, a user that is editing a document. If the user were to change a single letter, such as changing an "E" to an "F", only a few pixels of the video image would change. However, based upon this change, the resulting document is dramatically different than the original document. A percentage threshold algorithm would not register this change and, therefore, would lead to a display error. A percentage threshold algorithm, by only looking at the number of pixels within a block that have changed, generally fails to recognize a video image change in which a few pixels have changed substantially. However, the NRDT sub-algorithm used by the present invention, by virtue of its two-level threshold, will recognize that such a block of pixels has significantly changed between successive frames of video.

Smoothing:

When the NRDT sub-algorithm determines that a block of pixels has changed, the digital data that represents this block is further processed by a smoothing sub-algorithm. This sub-algorithm reduces the noise introduced during the analog-to-digital conversion.

First, each digital pixel representation is converted to a representation that uses a lower quantity of bits for each pixel. It is known in the art to compress color video by using a fewer number of bits to represent each color of
5 each pixel. For example, a common video standard uses 8 bits to represent each of the red, green, and blue components of a video signal. Because 24 total bits are used to represent a pixel, this representation is commonly referred to as "24 bit RGB representation". If only the
10 four most significant bits of the red, green, and blue components of the pixel are used to represent its color in lieu of all eight bits, the size of the data used to represent the block of pixels, and thus a frame of video, is reduced by fifty percent.

15 This method of compression is simple and generally degrades the quality of the video. In contradistinction, the smoothing sub-algorithm of the present invention incorporates a more intelligent method of compression. This method uses a Color Code Table ("CCT") to map specific
20 RGB representations to more compact RGB representations. Both the compression and decompression algorithms of the present invention use the same CCT. However, different color code tables may be chosen depending on the available

bandwidth, the capabilities of the local display device,
etc.

For each block of pixels, a histogram of pixel values
is created and sorted by frequency such that the smoothing
5 sub-algorithm may determine how often each pixel value
occurs. Pixel values that occur less frequently are
compared to pixel values that occur more frequently. To
determine how similar pixel values are, a distance value is
calculated based upon the color values of the red, green,
10 and blue ("RGB") components of each pixel. During the
histogram analysis, a map of RGB values to color codes
(i.e., a CCT) is created. If a less frequently occurring
pixel value needs to be adjusted to a similar, more
frequently occurring pixel value, the CCT is used to map
15 the less frequently occurring pixel value to the color code
of the more frequently occurring pixel value. Thus, the
noise is efficiently removed from each block and the number
of bits used to represent each pixel is reduced.

For illustrative purposes, suppose that an 8x8 pixel
20 block is being processed. Further suppose that of the 64
pixels in the current block, 59 are blue, 4 are red, and 1
is light blue. Further assume that a low frequency
threshold of 5 and a high frequency threshold of 25 are
used. In other words, if a pixel value occurs less than 5

times within a block, it is considered to have a low frequency. Similarly, if a pixel value occurs more than 25 times within a block, it is considered to have a high frequency. In the preferred embodiment of the present invention, the smoothing sub-algorithm ignores pixel values occurring between these two thresholds. Therefore, in the present example, the smoothing sub-algorithm determines that the red and light blue pixels occur with low frequency, and the blue pixels occur with high frequency.

In the next step, the values of the 4 red pixels and the 1 light blue pixel are compared with the value of the 59 blue pixels. In this step, a pre-determined distance threshold is used. If the distance between the less frequent pixel value and the more frequent pixel value is within this distance threshold, then the less frequent pixel value is converted to the more frequent pixel value. Therefore, in our present example, it is likely that the light blue pixel is close enough in value to the blue pixel that its distance is less than the distance threshold.

Consequently, the light blue pixel is mapped to the blue pixel. In contrast, it is likely that the distance between the red and blue pixels exceeds the distance threshold and, therefore, the red pixel is not mapped to the blue pixel. With the smoothing sub-algorithm of the present invention,

although the red pixels occur rarely, the distance between the red pixel value and the blue pixel value is large enough that the red pixels are not converted to blue pixels. In this manner, the smoothing sub-algorithm of the present invention increases the redundancy in compared images by eliminating changes caused by superfluous noise introduced during the analog-to-digital conversion while retaining real changes in the video image.

Caching:

After the smoothing sub-algorithm has been applied to the digital video image data, an optional caching sub-algorithm may be applied to further minimize the bandwidth required for transmitting the video images. The caching sub-algorithm uses a cache of previously transmitted blocks of pixels. Similar to the NRDT sub-algorithm, the caching sub-algorithm is performed on a block of pixels within the video frame. Again, any block size may be used (e.g., 8x8, 16x16, 32x32 or 64x32).

First, the caching sub-algorithm performs a cache check, which compares the current block of pixels with blocks of pixels stored in the cache. The size of the cache may be arbitrarily large. Large caches generally yield a higher percentage of "cache hits." However, memory and hardware requirements increase when the size of the

cache is increased. Furthermore, the number of comparisons, and thus the processing power requirements, also increases when the size of the cache increases.

A "cache hit" occurs when a matching block of pixels is located within the cache. A "cache miss" occurs if a matching block of pixels is not found in the cache. When a cache hit occurs, the new block of pixels does not have to be retransmitted. Instead, a message and a cache entry identification ("ID") are sent to the remote participant equipment. Generally, this message and cache entry ID will consume less bandwidth than that required to transmit an entire block of pixels.

If a "cache miss" occurs, the new block of pixels is compressed and transmitted to the user workstation. Also, both the RMU and user workstation update their respective cache by storing the new block of pixels in the cache. Since the cache is of limited size, older data is overwritten. One skilled in the art is aware that various algorithms can be used to decide which older data should be overwritten. For example, a simple algorithm can be employed to overwrite the oldest block of pixels within the cache, wherein the oldest block is defined as the least recently transmitted block.

In order to search for a cache hit, the new block of pixels must be compared with all corresponding blocks of pixels located within the cache. There are several ways in which this may be performed. In one embodiment, a cyclic
5 redundancy check ("CRC") is computed for the new block of pixels and all corresponding blocks of pixels. The CRC is similar to a hash code for the block. A hash code is a smaller, yet unique, representation of a larger data source. Thus, if the CRCs are unique, the cache check
10 process can compare CRCs for a match instead of comparing the whole block of pixels. If the CRC of the current block of pixels matches the CRC of any of the blocks of pixels in the cache, a "cache hit" has been found. Because the CRC is a smaller representation of the block, less processing
15 power is needed to compare CRCs. Furthermore, it is possible to construct a cache in which only the CRCs of blocks of pixels are stored at the remote participant locations. Thus, comparing the CRCs in lieu of comparing a full block of pixels saves processor time and thus improves
20 performance.

Bit Splicing/Compression:

Once the NRDT, smoothing, and optional caching sub-algorithms are performed, each block of pixels that must be
25 transmitted is compressed. In the preferred embodiment of

the present invention, each block is compressed using the Joint Bi-level Image Group ("JBIG") lossless compression algorithm.

The JBIG compression algorithm was designed for black
5 and white images, such as those transmitted by facsimile machines. However, the compression algorithm utilized by the present invention can compress and transmit color video images. Therefore, when utilizing the JBIG compression algorithm, the color video image must be bit-sliced, and
10 the resulting bit-planes must be compressed separately.

A bit plane of a color video image is created by extracting a single bit from each pixel color value in the color video image. For example, if 8 bits are used to represent the color of the pixel, then the color video
15 image is divided into 8 bit planes. The compression algorithm, in conjunction with the CCT discussed above, transmits the bit plane containing the most significant bits first, the bit plane containing the second most significant bits second, etc. The CCT is designed such
20 that the most significant bits of each pixel color are stored first and the lesser significant bits are stored last. Consequently, the bit planes transmitted first will always contain the most significant data, and the bit planes transmitted last will always contain the least

significant data. Thus, the remote video monitor will receive video from the RMU progressively, receiving and displaying the most significant bits of the image before receiving the remaining bits. Such a method is less
5 sensitive to changes in bandwidth and will allow a user to see the frame of video as it is transmitted, rather than waiting for all details of the frame to be sent.

After compression of the video signals is complete, the resulting video signals are transmitted to either
10 Ethernet connector 205 or communications port connector 206 via switch 390.

Referring back to FIG. 3A, RMU 109 also contains a power supply 221 which provides power to RMU 109. Preferably, power supply 221 is a redundant power supply
15 which contains backup circuitry in case the main circuitry fails. Power supply 221 receives power through power port 223 from an external power supply. The power to RMU is controlled by reset circuitry 225 which is interfaced directly to CPU 207. Reset circuitry 225 is utilized to
20 turn the power on/off and reset RMU 109.

RMU 109 also contains local KVM port 227 interfaced to CPU 207. Local KVM port 227 allows for connection of local keyboard 123, video monitor 127, and cursor control device 125 to RMU 227 via cable 129 (FIG. 1). Local keyboard 123,

video monitor 127, and cursor control device 125 may be utilized for onsite control of the attached serial devices 111a and 111b, servers 113a and 113b, computers 115a and 115b, and power supply 117.

5 Option menu circuit 229, under control of CPU 207, provides the option menu to a user of the present invention. As previously discussed, the option menu contains menus for selecting a serial device, a remote server or computer, or options to control the power to all
10 devices connected to power supply 117.

 To utilize the system of the present invention, a user first initiates a remote management session at user workstation 101 and enters the required username and password. However, any unique combination of
15 authentication information may be utilized. User workstation 101 packetizes the entered information and routes it to Internet/LAN/WAN 108 via communication line 119 and then to RMU 109 via communication line 121. The entered data is received at CPU 207 via RJ-45 connector 201
20 (or alternatively RJ-11 connector 202). Ethernet connector 205 removes the network protocol and transmits the received keyboard and/or cursor control device signals to CPU 207. CPU 207 utilizes a lookup table containing all user profiles stored in the system to authenticate the user.

Different user profiles may be given different levels of access to the system. For example, certain users may only be able to access and operate computers 115a and 115b and be restricted from operating servers 113a and 113b, serial
5 devices 111a and 111b, and power supply 117.

Once a user has been authenticated, option menu circuit 229 produces an option menu containing all the devices attached to RMU 109. In this case, the attached devices include serial devices 111a and 111b, servers 113a
10 and 113b, computers 115a and 115b, and power supply 117. However, it would be apparent to one skilled in the art that RMU 109 may accommodate any number of serial devices, servers, computers, and associated power supplies. The option menu produced by option menu circuit 229 is
15 compressed by video processor 212 and packetized by Ethernet connector 205 and then transmitted to user workstation 101 through RJ-45 connector 201, communication line 121, Internet/LAN/WAN 108, and communication line 119, in that order. The option menu is depacketized and
20 decompressed at user workstation 101 for display on video monitor 105. The user then utilizes keyboard 103 and cursor control device 107 to select the desired device from the option menu. The user-entered keyboard and cursor control device signals are then encoded by user workstation

101, transmitted to RMU 109 via Internet/LAN/WAN 108, and subsequently decoded by CPU 207 located in RMU 109. CPU 207 interprets the received keyboard and cursor control device signals and interfaces the user with the selected
5 device as previously described.

If the user selects to be interfaced with servers 113a or 113b or computers 115a and 115b, the video signal of the selected device is displayed on video monitor 105. The video signal initially arrives from the selected device at
10 KVM port 219 and is routed to KVM port header 217. The video signal is then routed to frame grabber 215 which converts the analog video signal to a digital signal. The resulting digitized video signal is then routed to CPU 207 through PCI riser card 209. CPU 207 then determines the
15 correct location to transmit the video signal (i.e., to local KVM port 227 or video processor 212). If the video signal is routed to local KVM port 227, the video signal is displayed on local video monitor 127. Alternatively, if the video signal is routed to video processor 212, it is
20 compressed by video processor 212 and packetized by either Ethernet connector 205 or communications port connector 206 for transmission via communication line 121 through either RJ-45 port 201 or RJ-11 port 202. Ethernet connector 205 or communications port connector 206 also appends any other

signals (i.e., keyboard signals, cursor control device signals, etc.) onto the compressed video signal for transmission to user workstation 101.

To switch to another connected device, the user
5 presses a "hotkey" such as "printscreen" or "F1" on keyboard 103 attached to user workstation 101 (FIG. 1). This causes option menu 229 to open an option menu allowing the user to select a new serial device, server, computer, or modify the power supply to one of the connected devices.

10 Referring now to FIG. 4, depicted is a flowchart illustrating the operation of the compression algorithm utilized by video processor 212 in the preferred embodiment of the present invention. The compression algorithm is executed internal to RMU 109 by video processor 212 (FIG.
15 3). The digitized video signal is initially stored in a raw frame buffer (step 402), which is one of the frame buffers 380 (FIG. 3D). At this point, the compression algorithm is performed to process the captured video data contained in the raw frame buffer and prepare it for
20 transmission to user workstation 101.

The first step of the compression algorithm is the NRDT (step 403). The NRDT sub-algorithm is also executed internal to RMU 109 by video processor 212 (FIG. 3). The NRDT sub-algorithm determines which blocks of pixels, if

any, have changed between the current frame and the compare frame, also discussed above.

In the preferred embodiment, the video frame is first divided into 64x32 pixel blocks. Subsequently, the NRDT sub-algorithm is applied to each block of pixels independently. Alternative embodiments of the present invention may utilize smaller or larger blocks depending on criteria such as desired video resolution, available bandwidth, etc.

Next, the NRDT sub-algorithm employs a two-threshold model to determine whether differences exist between a block of pixels in the current frame and the corresponding block of pixels in the compare frame. These two thresholds are the pixel threshold and the block threshold.

First, each pixel of the pixel block is examined to determine if that pixel has changed relative to the corresponding pixel of the corresponding block in the compare frame. The distance value of each of the three colors (i.e., red, green, and blue) of each pixel in relation to the corresponding compare pixel is calculated, as described in greater detail below with respect to FIG. 7. If the distance value is larger than the pixel threshold (i.e., the first threshold of the two-threshold

model), this distance value is added to a distance sum value.

Then, after all pixels within the pixel block have been examined, if the resulting distance sum value is
5 greater than the block threshold (i.e., the second threshold of the two-threshold model), the block is determined to have changed. Every block of pixels in the video frame undergoes the same process. Therefore, after this process has been applied to an entire video frame, the
10 process will have identified all pixel blocks that the process has determined have changed since the previous video frame. At this point, the compare frame is updated with the changed pixel blocks. However, the pixel blocks of the compare frame that correspond to unchanged pixel
15 blocks of the current frame will remain unchanged. In this manner, the two-threshold model used by the NRDT sub-algorithm eliminates pixel value changes that are introduced by noise created during the analog to digital conversion and also captures the real changes in the video
20 frame.

After the video data is processed by the NRDT sub-algorithm, it is next processed by the smoothing sub-algorithm (step 419). The smoothing sub-algorithm is designed to create a smooth, higher-quality video image by

reducing the roughness of the video image caused by noise introduced during the analog to digital conversion.

The smoothing sub-algorithm first converts the pixel representation that resulted from the NRDT sub-algorithm
5 into a pixel representation that uses a lesser quantity of bits to represent each pixel. This is performed using a CCT that is specially organized to minimize the size of the pixel representation. The smoothing sub-algorithm uses the CCT to choose color codes with the least number of 1-bits
10 for the most commonly used colors. For example, white and black are assumed to be very common colors. Thus, white is always assigned 0 and black is always assigned 1. That is, white will be represented by a bit value of 0 on all planes. Black, the next most common color, will show up as
15 a bit value of 1 on all but one plane. This reduces the quantity of data to be compressed by the compression algorithm. Then, for each pixel in the block, a color code is assigned. Simultaneously, a histogram of color codes is created to store the number of occurrences of each of the
20 unique colors in the block of pixels. This histogram of color codes is then sorted to produce a list of color codes from the least number of occurrences to the dominant number of occurrences.

Once the sorted list of color codes is created, the next step is to merge colors. Working from the beginning of the sorted list, the smoothing sub-algorithm compares the least frequently occurring colors to the more frequently occurring colors. If the less frequently occurring color is very similar to a more frequently occurring color, then the pixels having the less frequently occurring color will be changed to the more frequently occurring color. Determination of whether two colors are similar is performed by calculating the distance between the three-dimensional points of the RGB space. The formula is:

$$D = \sqrt{(R_1 - R_2)^2 + (G_1 - G_2)^2 + (B_1 - B_2)^2}$$

where D is the distance, R_1 is the red value of the low frequency pixel, R_2 is the red value of the high frequency pixel, G_1 is the green value of the low frequency pixel, G_2 is the green value of the high frequency pixel, B_1 is the blue value of the low frequency pixel, and B_2 is the blue value of the high frequency pixel. If the distance is within a distance threshold, the two colors are determined to be similar. In the preferred embodiment of the present invention, system performance is increased by squaring the distance threshold and comparing this value with the sum of the squares of the RGB differences. This step eliminates

taking the square root of the sum, which requires a greater amount of processing time.

Each block of pixels is filtered for noise and translated from a RGB representation to a color code representation. The noise that is introduced by LCD controller 215 (FIG. 3) during conversion of the analog signals to digital signals distorts the values of some pixels. Thus, the smoothing sub-algorithm corrects distorted pixels. The smoothing sub-algorithm minimizes noise by reducing the number of different colors present in each video image block. Further, such smoothing creates an image with greater redundancy, thus yielding higher compression ratios.

After smoothing, caching is performed (step 421). Caching is a sub-algorithm of the overall compression algorithm executed by video processor 212 of RMU 109 (FIG. 3). Caching requires RMU 109 (FIG. 3) to retain a cache of recently transmitted images. Such a cache can be implemented and stored in RAM 386 (FIG. 3D). The caching sub-algorithm compares the most recent block of pixels with the corresponding block of pixels in the video images stored in the cache (step 405). If the most recently transmitted block of pixels is the same as one of the corresponding blocks of pixels stored in the cache, the

5 caching sub-algorithm does not retransmit this portion of
the video image. Instead, a "cache hit" message is sent to
user workstation 101, which indicates that the most
recently transmitted block is already stored in the cache
(step 407). The "cache hit" message contains information
regarding which cache contains the corresponding block of
pixels, thereby allowing user workstation 101 to retrieve
the block of pixels from its cache and use it to create the
video image to be displayed on its attached video display
10 device.

The next step in the process, step 409, determines if
the NRDT determined that the block of pixels has changed
since the corresponding block of pixels in the compare
frame. This step can also be implemented before or in
15 parallel with step 405. Also, steps 421, 405, and 407 may
be eliminated entirely.

The main purpose of step 409 is to determine whether
the block has changed since the last frame. If the block
has not changed, there is no need to send an updated block
20 to user workstation 101. Otherwise, if the block of pixels
has changed, it is prepared for compression (step 411). In
the preferred embodiment, step 409 uses a different
technique than step 405. With two ways of checking for
redundancy, higher compression will result. Both steps 409

and 411 are executed by a caching sub-algorithm executed by microprocessor 388 of video processor 212 (FIG. 3D).

For any areas of the image that have changed, the cache is updated, and the data is compressed before being
5 sent to the server stack. In the preferred embodiment, the image is compressed using the IBM JBIG compression algorithm. JBIG is designed to compress black and white images. However, the present invention is designed to transmit color video images. Therefore, bit planes of the
10 image are extracted (step 411), and each bit plane is compressed separately (step 413). Finally, the compressed image is transmitted to server stack 417 (step 415), which transmits the data to switch 390 (FIG. 3D).

FIG. 5A and FIG. 5B provide detailed flowcharts of a
15 preferred embodiment of the compression process. The digital representation of the captured video image is transferred and stored in either frame buffer 0 503 or frame buffer 1 505. A frame buffer is an area of memory that is capable of storing one frame of video. The use of
20 two frame buffers allows faster capture of image data. The captured frames of video are stored in frame buffer 0 503 and frame buffer 1 505 in an alternating manner. This allows the next frame of video to be captured while compression is being performed on the previous frame of

video. In video processor 212, frame buffer 0 503 and frame buffer 1 505 comprise a portion of frame buffers 380 (FIG. 3D).

An NRDT test is performed on each block of pixels stored in frame buffer 0 503 and frame buffer 1 505 (step 519), which compares each block of the captured video image to the corresponding block of the previously captured video image. Step 519 compares blocks of pixels from the video image stored in the current raw frame buffer (i.e., frame buffer 0 503 or frame buffer 1 505) with the corresponding block of pixels stored in compare frame buffer 521. This step is discussed in greater detail below with respect to FIGS. 6A and 6B.

If step 519 determines that the current block of pixels has changed, then nearest color match function processes the video images contained in frame buffer 0 503 and frame buffer 1 505 (step 509) in conjunction with the information contained in the client color code table ("CCT from client") 511, which is stored in flash memory 239 (FIG. 3). The nearest color match function can be executed as software by microprocessor 388. A detailed explanation of the nearest color match function is provided below with respect to FIG. 6.

The CCT obtained from CCT 513 by the nearest color match function is used for color code translation (step 515), which translates the digital RGB representation of each pixel of the changed block of pixels to reduce the amount of digital data required to represent the video data. Color code translation (step 515) receives blocks of pixels that the NRDT sub-algorithm (step 519) has determined have changed relative to the previous captured video image. Color code translation then translates this digital data into a more compact form and stores the result in coded frame buffer 517. Coded frame buffer 517 can be implemented as a portion of RAM 386 (FIG. 3D).

Alternatively, steps 509 and 515 may be performed in parallel with step 519. Performing these steps in parallel reduces the processing time required for each block of pixels that has changed. In this scenario, steps 509 and 515 are performed in anticipation of the block of pixels having changed. If this is the case, the processing for steps 509 and 515 may be completed at the same time as the processing for step 519 is completed. Therefore, the algorithm may move directly to step 523 from step 509 without having to wait for the processing of steps 509 and 515. Otherwise, if step 519 determines that the block of pixels has not changed, and therefore the results of steps

509 and 515 are not required, these results may simply be discarded.

Upon completion of step 515, caching begins by performing a cyclical redundancy check (CRC) (step 523).

5 Cyclic redundancy check (CRC) is a method known in the art for producing a checksum or hash code of a particular block of data. The CRCs may be computed for two blocks of data and then compared. If the CRCs match, the blocks are the same. Thus, CRCs are commonly used to check for errors.

10 In the present invention, the CRC is used to compare a block of pixels with blocks of pixels stored in a cache. Thus, in step 523, the CRC is computed for each block of pixels that was determined to have changed by the NRDT sub-algorithm. The array of CRCs is stored in CRC array 525.

15 Turning next to FIG. 5B, depicted is an overview of the caching and bit splicing/compression sub-algorithms. This portion of the algorithm begins waiting for information from coded frame buffer 517 and CRC array 525 (step 527). Next, a decision is made as to whether a new
20 video mode has been declared (step 529). A new video mode can be declared if, for example, user workstation 101 has different bandwidth or color requirements. If a new video mode has been declared, all data is invalidated (step 531) and the sub-algorithm returns to step 527 to wait for new

information from coded frame buffer 517 and CRC array 525. Downscaler circuit 362 and/or upscaler circuit 364, located in LCD controller 215, may be utilized to adjust the outputted digitized video to be compatible with the new
5 video mode. Steps 527, 529, and 531 are all steps of the overall compression algorithm that is executed by microprocessor 388 (FIG. 3D).

If in step 529 it is deemed that a new video mode has not been declared, then the comparison of the current block
10 of pixel's CRC with the cached CRCs is performed (step 533). This block compares the CRC data of the current video frame contained in CRC array 525 with the cache of previous CRCs contained in block info array 535. Block info array 535 stores the cache of pixel blocks and the
15 CRCs of the pixel blocks and can be implemented as a device in RAM 386 (FIG. 3D). Step 533 is also a part of the overall compression algorithm executed by microprocessor 388 (FIG. 3D).

Next, if the current block of pixels is located within
20 the pixel block cache contained in block info array 535 (step 537), a cache hit message is sent to user workstation 101 and the block of pixels is marked as complete, or processed (step 539). Since user workstation 101 contains the same pixel block cache as RMU 109 (FIG. 3D), the cache

hit message simply directs user workstation 101 to use a specific block of pixels contained in its cache to create the portion of the video image that corresponds to the processed block of pixels.

5 Next, a check is performed for unprocessed blocks of pixels (step 539). All blocks of pixels that need to be processed, or updated, are combined to create a compute next update rectangle. If there is nothing to update (i.e., if the video has not changed between frames), then
10 the algorithm returns to step 527 (step 543). Thus, the current frame will not be sent to the remote participation equipment. By eliminating the retransmission of a current frame of video, the sub-algorithm reduces the bandwidth required for transmitting the video.

15 If, however, there are areas of the image that need to be updated, the update rectangle is first compressed. The update rectangle must first be bit sliced (step 545). A bit plane of the update rectangle is constructed by taking the same bit from each pixel of the update rectangle.

20 Thus, if the update rectangle includes 8-bit pixels, it can be deconstructed into 8 bit planes. The resulting bit planes are stored in bit plane buffer 547. Again, steps 541, 543, and 545 are all part of the bit

splicing/compression sub-algorithm executed by
microprocessor 388 of RMU 109 (FIG. 3).

Each bit plane is compressed separately by the
compression sub-algorithm (step 549). In this case,
5 compression is performed on each bit plane and the
resulting data is sent to server stack 417 (step 551). In
the preferred embodiment, compression is performed by video
compression device 382 (FIG. 3) (step 549). Thereafter,
the compressed bit planes are sent to switch 390 (FIG. 3D).

10 Since the preferred embodiment captures frames 20
times per second, it is necessary to wait 300 ms between
video frame captures. Thus, the algorithm waits until 300
ms have passed since the previous frame capture before
returning the sub-algorithm to step 527 (step 553).

15 Referring now to FIG. 6, illustrated is the nearest
color match function (step 509 of FIG. 5A) that selectively
maps less frequently occurring colors to more frequently
occurring colors using a CCT. Nearest color match function
509 processes each block of pixels of the video image
20 stored in frame buffer 0 503 or frame buffer 1 505
successively. As shown in FIG. 6, a block of pixels is
extracted from the video image stored in frame buffer 0 503
or frame buffer 1 505 (step 600). In the preferred

embodiment, the extracted block has a size of 64 by 32 pixels, however, any block size may be utilized.

The nearest color match function eliminates noise introduced by the A/D conversion by converting less frequently occurring pixel values to similar, more frequently occurring pixel values. The function utilizes histogram analysis and difference calculations. First, nearest color match function 509 generates a histogram of pixel values (step 601). The histogram measures the frequency of each pixel value in the block of pixels extracted during step 600. The histogram is sorted, such that a list of frequently occurring colors (popular color list 603) and a list of least frequently occurring colors (rare color list 605) are generated. The threshold for each list is adjustable.

Then, nearest color match function 509 analyzes each low frequently occurring pixel to determine if the pixel should be mapped to a value that occurs often. First, a pixel value is chosen from rare color list 605 (step 607). Then, a pixel value is chosen from popular color list 603 (step 609). These distance between these two values is then computed (step 611). In this process, distance is a metric computed by comparing the separate red, green and

blue values of the two pixels. The distance value D may be computed in a variety of ways. One such example is:

$$D = (R_1 - R_2)^2 + (G_1 - G_2)^2 + (B_1 - B_2)^2$$

In this formula, R1 is the red value of the low frequency
5 pixel, R2 is the red value of the high frequency pixel, G1
is the green value of the low frequency pixel, G2 is the
green value of the high frequency pixel, B1 is the blue
value of the low frequency pixel, and B2 is the blue value
of the high frequency pixel.

10 This formula yields a distance value, D, which
indicates the magnitude of the similarity or difference of
the colors of two pixels, such as a less frequently
occurring pixel versus a more frequently occurring pixel.
The goal of the sub-algorithm is to find a more frequently
15 occurring pixel having a color that yields the lowest
distance value when compared to the color of a less
frequently occurring pixel. Therefore, a comparison is
performed for each computed distance value (step 613).
Every time a distance value is computed that is less than
20 all previous distance values, the distance value is written
to the closest distance variable (step 615).

Once it is determined that all more frequently
occurring pixels have been compared to less frequently
occurring pixels (step 617), a computation is performed to

determine if the lowest occurring D is within a predefined threshold (step 619). If this D is within the predefined threshold, CCT 513 is updated by mapping the low frequently occurring pixel to the color code value of the high frequently occurring pixel that yielded this D value (step 621). This process is repeated for all low frequency pixels and CCT 513 is updated accordingly.

Turning to FIG. 7, RGB NRDT step 519 (FIG. 5A) is illustrated in further detail. This process operates on every block of pixels. Current pixel block 700 represents a block of pixels of the video image contained in the current frame buffer (i.e., frame buffer 0 503 or frame buffer 1 505 (FIG. 5A)). Previous pixel block 701 contains the corresponding block of pixels of the video image contained in compare frame buffer 521 (FIG. 5A). Step 519 begins by extracting corresponding pixel values for one pixel from the current pixel block 700 and previous pixel block 701 (step 703). Then, the pixel color values are used to calculate a distance value, which indicates the magnitude of the similarity or difference between the colors of the two pixels (step 705). In the preferred embodiment of the present invention, the distance value is computed using the following formula:

$$D = (R_1 - R_2)^2 + (G_1 - G_2)^2 + (B_1 - B_2)^2$$

As before, R1, G1, and B1 are the red, green and blue values respectively of the frame buffer pixel. Similarly, R2, G2, and B2 are the red, green and blue values respectively for the compare frame buffer pixel.

5 Next, the computed distance value D is compared with a pixel threshold (step 707). If D is greater than the pixel threshold, it is added to an accumulating distance sum (step 709). If the value of D is less than the pixel threshold, the difference is considered to be insignificant
10 (i.e., noise) and it is not added to the distance sum.

 This process of computing distance values and summing distance values that are greater than a predefined pixel threshold continues until it is determined that the last pixel of the block of pixels has been processed (step 711).
15 Once the last pixel is reached, the distance sum is compared with a second threshold, the block threshold (step 713). If the distance sum is greater than the block threshold, the current block of pixels designated as changed as compared to the corresponding block of pixels
20 from the previously captured frame. Otherwise, if the distance sum is less than the block threshold, the block of pixels is designated as unchanged.

 If the block of pixels is designated as changed, step 715 is executed. Step 715 sets a flag that indicates that

the particular block of pixels has changed. Furthermore, the new block of pixels is written to compare frame buffer 521 (FIG. 5A) to replace the corresponding previous block of pixels.

5 Otherwise, if the distance sum does not exceed the block threshold, the block is designated unchanged and, a flag is set to indicate that this block of pixels does not need to be re-transmitted to the remote participation equipment (step 721). Rather, the remote participation
10 equipment will recreate the portion of the video image represented by the block of pixels using the same block of pixels displayed for the previous frame of video. At this point the system computers CRCs for changed blocks of pixels (step 523 of FIG. 5A) as discussed in greater detail
15 above with respect to FIG. 5A.

FIG. 8 further illustrates the two level thresholding used by the NRDT sub-algorithm shown in FIG. 7. For illustrative purposes only, 4x4 blocks of pixels are shown. Each pixel is given red, green, and blue color values that
20 range from 0 to 255, as is commonly performed in the art. A pixel having red, green, and blue values of 0 represents a black pixel, whereas a pixel having red, green, and blue values of 255 represents a white pixel. Previous pixel block 751 is a block of pixels grabbed from compare frame

buffer 521 (FIG. 5A). Previous pixel 1 752 is the pixel in the upper, left corner of previous pixel block 751. Since every pixel of previous pixel block 751 has a value of 0, previous pixel block 751 represents a 4x4 pixel area that
5 is completely black.

Current pixel block 753 represents the same spatial area of the video frame as previous pixel block 751, but it is one frame later. Here current pixel 1 754 is the same pixel 1 as previous pixel 1 752, but is one frame later.
10 For simplicity, suppose a small white object, such as a white cursor, enters the area of the video image represented by previous pixel block 751. This change occurs in current pixel 1 754 of current pixel block 753. In current pixel block 753, the majority of the pixels
15 remained black, but current pixel 1 754 is now white, as represented by the RGB color values of 255, 255, and 255.

Further suppose that noise has been introduced by the A/D conversion, such that previous pixel 755 has changed from black, as represented by its RGB values of 0, 0, and
20 0, to gray. The new gray color is represented by the RGB values of 2, 2, and 2 assigned to current pixel 756.

Further suppose that the pixel threshold is 100, and the block threshold is 200. The NRDT sub-algorithm calculates the distance value between each pixel of current

pixel block 753 and previous pixel block 751. The formula used in the preferred embodiment of the present invention, as discussed above with respect to FIG. 7, is:

$$D = (R_1 - R_2)^2 + (G_1 - G_2)^2 + (B_1 - B_2)^2$$

5 Therefore, the distance value between current pixel 1 754 and previous pixel 1 752 is:

$$D = (255 - 0)^2 + (255 - 0)^2 + (255 - 0)^2$$

or 195,075. This distance value is added to the distance sum because 195,075 exceeds the pixel threshold of 100.

10 However, the distance value between the black previous pixel 755 and the gray current pixel 756 is not added to the distance sum because the distance between the pixels, as calculated using the above distance formula, equals 12, which does not exceed the pixel threshold of 100.

15 Similarly, the distance value is computed for all of the remaining pixels in the two pixel blocks. Each of these distance values equals zero, therefore, since these distance values are less than the pixel threshold, they are not added to the distance sum.

20 Consequently, after the distance values for all pixels have been processed, the distance sum equals 195,075. Since this value is greater than the block threshold of 200, the block is designated. This example illustrates the advantages of the two-level thresholding feature of the

NRDT sub-algorithm. That is, the noise that occurred in current pixel 756 of current pixel block 753 was ignored, whereas the real change in video that occurred in current pixel 1 754 of current pixel block 753 was recognized.

5 Turning finally to FIG. 9, shown is a flowchart of the decompression algorithm executed by user workstation 101 (FIG. 1). The decompression algorithm begins by waiting for a message (step 801). This message is transmitted from server stack 417 of RMU 109 to user workstation 101.

10 Thereafter, user workstation 101 receives the information and writes the data to client stack 803. Client stack 803 may be a register or some other device capable of permanently or temporarily storing digital data. In one embodiment of the present invention, messages are
15 transmitted using the TCP/IP communication protocol. In this scenario, client stack 803 is the local TCP/IP stack. Other embodiments may use a protocol other than TCP/IP. However, irrespective of the communication protocol, the present invention uses client stack 803 to store received
20 messages for processing.

Once a message is received in client stack 803, it is processed to determine whether the message is a new video mode message (step 805). A new video mode message may be sent for a variety of reasons including a bandwidth change,

a change in screen resolution or color depth, a new client, etc. This list is not intended to limit the reasons for sending a new video mode message, but instead to give examples of when it may occur. If the message is a new
5 video mode message, application layer 823 is notified of the new video mode (step 807). According to the preferred embodiment, application layer 823 is software executed by user workstation 101 that interfaces with the input and output devices of user workstation 101 (i.e., keyboard 103,
10 video monitor 105, and cursor control device 107). Any video updates must therefore be sent to application layer 823. Also, the old buffers are freed, including all memory devoted to storing previously transmitted frames, and new buffers are allocated (step 809). The decompression
15 algorithm then returns to step 801.

If the new message is not a video mode message, the message is further processed to determine if it is a cache hit message (step 811). If yes, the cache hit message is deciphered to determine which block of pixels, of the
20 blocks of pixels stored in the three cache frame buffers 815, should be used to reconstruct the respective portion of the video image. Although three cache frame buffers 815 are used in the preferred embodiment of the present invention, any quantity of cache frame buffers may be used

without departing from the spirit of the invention. Cache frame buffers 815 store the same blocks of pixels that are stored in the cache frame buffers located internal to RMU 109 (FIG. 3). Thus, the cache hit message does not include
5 video data, but rather simply directs the remote participation equipment as to which block of pixels contained in the cache frame buffer 815 should be sent to merge frame buffer 817. The block of pixels contained within the specified cache is then copied from cache frame
10 buffer 815 to merge buffer 817 (step 813). Finally, application layer 823 is notified that an area of the video image has been updated (step 825). Merge buffer 817 contains the current representation of the entire frame of video in color code pixels. Application layer 823 copies
15 the pixel data from merge buffer 817 and formats the data to match the pixel format of the connected video monitor 105 (step 819). Thereafter, the formatted pixel data is written to update frame buffer 821, which then transmits the data to video monitor 105. Alternatively, in lieu of a
20 video monitor, the formatted pixel data may be written to a video card, memory, and/or any other hardware or software commonly used with video display devices.

Further, if the new message is not a new video mode or cache hit message, it is tested to determine if it is a

message containing compressed video data (step 827). If the message does not contain compressed video data, the decompression algorithm returns to step 801 and waits for a new message to be transmitted from server stack 417.

5 Otherwise, if the message does contain compressed video data, the data is decompressed and transferred to bit plane frame buffer 833 (step 829). As described above, the preferred embodiment incorporates the JBIG lossless compression technique. Therefore, decompression of the
10 video data must be performed for each individual bit plane. After each bit plane is decompressed, it is merged with previously decompressed bit planes, which are stored in bit plane frame buffer 833 (step 829). When a sufficient number of bit planes have been merged, the merged data
15 contained in bit plane frame buffer 833 is transferred to merge frame buffer 817 (step 831). Alternatively, individual bit planes may be decompressed and stored directly in merge frame buffer 817, thereby eliminating step 831. When all of the data required to display a full
20 frame of video is transferred to merge frame buffer 817, application layer 823 copies the data in merge frame buffer 817 to update frame buffer 821 (step 819). Thereafter, the data is transferred to video monitor 105.

In an alternate embodiment, the video displayed on video monitor 105 can be updated after each bit plane is received. In other words, a user does not have to wait until the whole updated frame of video is received to
5 update portions of the displayed video. This alternative method is desirable when the bandwidth available for video transmission varies. Also, this progressive method of updating the video display is one of the advantages of using the JBIG compression algorithm.

10 Next, the decompression algorithm determines whether all of the color code data from one field of the current video frame has been received (step 835). If a full field has not been received, the decompression algorithm returns to step 801 and waits for the remainder of the message,
15 which is transmitted from server stack 417 to client stack 803 in the form of a new message. Otherwise, if a full field has been received, the decompression method notifies application layer 823 (step 837). Similar to that described above with respect to processing cache hit
20 messages, this notification directs application layer 823 to read the data in merge frame buffer 817 and convert it to the current screen pixel format (step 819). Thereafter, the formatted data is written to update frame buffer 821, which transmits the data to video monitor 105.

After a full field has been received and application layer 823 has been notified, a second determination is made to determine if the full field is the last field included in the message. If it is, the newly decompressed block of pixels is written to one of the cache frame buffers 815 (step 841). Otherwise, the decompression algorithm returns to step 801 and continues to wait for a new message. Preferably, the new block of pixels written to cache frame buffer 815 overwrites the oldest block of pixels contained therein. Step 841 ensures that the cache is up-to-date and synchronized with the cache of RMU 109. After the completion of the cache update, the decompression algorithm returns to step 801.

While the present invention has been described with reference to the preferred embodiments and several alternative embodiments, which embodiments have been set forth in considerable detail for the purposes of making a complete disclosure of the invention, such embodiments are merely exemplary and are not intended to be limiting or represent an exhaustive enumeration of all aspects of the invention. The scope of the invention, therefore, shall be defined solely by the following claims. Further, it will be apparent to those of skill in the art that numerous changes may be made in such details without departing from

the spirit and the principles of the invention. It should be appreciated that the present invention is capable of being embodied in other forms without departing from its essential characteristics.